

# Calculus of Finite Differences

## 2.1. DIFFERENCE SCHEMES

The difference schemes deals with the variation in the function when the independent variable changes by equal intervals. It is only a question of notation what the differences are called.

(i) **Finite differences.** Suppose the function  $y = f(x)$  has the values  $y_0, y_1, y_2, \dots, y_n$  for the values of  $x = x_0, x_0 + h, x_0 + 2h, \dots, x_0 + nh$ . To determine the values of  $f(x)$  and  $f'(x)$  is based on the principle of finite differences which requires following differences.

(ii) **Forward differences.** The differences  $y_1 - y_0, y_2 - y_1, \dots, y_n - y_{n-1}$  are called **first forward differences** and are denoted by  $\Delta y_0, \Delta y_1, \dots, \Delta y_{n-1}$  where  $\Delta$  is known as **forward difference operator**. Thus the first forward differences are given by

$$\Delta y_k = y_{k+1} - y_k.$$

Similarly, the second forward differences are

$$\begin{aligned} \Delta^2 y_k &= \Delta y_{k+1} - \Delta y_k \\ &= y_{k+2} - y_{k+1} - y_{k+1} + y_k \\ &= y_{k+2} - 2y_{k+1} + y_k. \end{aligned}$$

In general

$$\Delta^r y_k = \Delta^{r-1} y_{k+1} - \Delta^{r-1} y_k.$$

(iii) **Forward differences table :**

$x$	$y$	First Diff.	Second Diff.	Third Diff.	Fourth Diff.	Fifth Diff.
$x_0$	$y_0$					
$x_0 + h$	$y_1$	$\Delta y_0$				
$x_0 + 2h$	$y_2$	$\Delta y_1$	$\Delta^2 y_0$			
$x_0 + 3h$	$y_3$	$\Delta y_2$	$\Delta^2 y_1$	$\Delta^3 y_0$		
$x_0 + 4h$	$y_4$	$\Delta y_3$	$\Delta^2 y_2$	$\Delta^3 y_1$	$\Delta^4 y_0$	
$x_0 + 5h$	$y_5$	$\Delta y_4$	$\Delta^2 y_3$	$\Delta^3 y_2$	$\Delta^4 y_1$	$\Delta^5 y_0$

In this table  $\Delta y_0, \Delta^2 y_0, \Delta^3 y_0$  etc. are called the **leading differences**.

The operator  $\Delta$  obeys the following laws :

- (i)  $\Delta [f(x) \pm g(x)] = \Delta f(x) \pm \Delta g(x)$
- (ii)  $\Delta [c f(x)] = c \Delta f(x)$ ,  $c$  being a constant
- (iii)  $\Delta(c) = 0$ ,  $c$  being a constant.

(iv) **Backward differences.** The differences  $y_1 - y_0, y_2 - y_1, \dots, y_n - y_{n-1}$  are also called *first backward differences* and denoted by  $\nabla y_1, \nabla y_2, \dots, \nabla y_n$  respectively. Thus we have

$$\nabla y_k = y_k - y_{k-1}$$

and

$$\nabla^2 y_k = \nabla y_k - \nabla y_{k-1}$$

In general

$$\nabla^r y_k = \nabla^{r-1} y_k - \nabla^{r-1} y_{k-1}.$$

Thus we have a backward difference table as under :

$x$	$y$	First Diff.	Second Diff.	Third Diff.	Fourth Diff.	Fifth Diff.
$x_0$	$y_0$					
$x_0 + h$	$y_1$	$\nabla y_1$				
$x_0 + 2h$	$y_2$	$\nabla y_2$	$\nabla^2 y_2$			
$x_0 + 3h$	$y_3$	$\nabla y_3$	$\nabla^2 y_3$	$\nabla^3 y_3$	$\nabla^4 y_4$	
$x_0 + 4h$	$y_4$	$\nabla y_4$	$\nabla^2 y_4$	$\nabla^3 y_4$	$\nabla^4 y_5$	$\nabla^5 y_5$
$x_0 + 5h$	$y_5$	$\nabla y_5$	$\nabla^2 y_5$	$\nabla^3 y_5$		

(v) **Central differences.** If

$$y_1 - y_0 = \delta y_{1/2}, y_2 - y_1 = \delta y_{3/2}, \dots, y_n - y_{n-1} = \delta y_{n-1/2}.$$

Then these differences called **central differences** and  $\delta$  is called **central difference operator**.

Similarly we can define higher order central differences as

$$\delta y_{3/2} - \delta y_{1/2} = \delta^2 y_1, \delta y_{5/2} - \delta y_{3/2} = \delta^2 y_2$$

and

$$\delta^2 y_2 - \delta^2 y_1 = \delta^3 y_{3/2} \text{ and so on.}$$

The central difference table is given below :

$x$	$y$	First Diff.	Second Diff.	Third Diff.	Fourth Diff.	Fifth Diff.
$x_0$	$y_0$					
		$\delta y_{1/2}$				
$x_1$	$y_1$		$\delta^2 y_1$			
		$\delta y_{3/2}$		$\delta^3 y_{3/2}$		
$x_2$	$y_2$		$\delta^2 y_2$		$\delta^4 y_2$	
		$\delta y_{5/2}$		$\delta^3 y_{5/2}$		$\delta^5 y_{5/2}$
$x_3$	$y_3$		$\delta^2 y_3$		$\delta^4 y_3$	
		$\delta y_{7/2}$		$\delta^3 y_{7/2}$		
$x_4$	$y_4$		$\delta^2 y_4$			
		$\delta y_{9/2}$				
$x_5$	$y_5$					

(vi) Other difference operators :

(a) **Shift operator.** The operator which increases the argument  $x$  by  $h$  is called shift operator

$$E f(x) = f(x + h)$$

and

$$E^2 f(x) = f(x + 2h)$$

$$E^3 f(x) = f(x + 3h) \dots \text{etc.}$$

This operator  $E$  is called **shift operator**. The inverse operator  $E^{-1}$  is defined as

$$E^{-1} f(x) = f(x - h), E^{-2} f(x) = f(x - 2h) \dots \text{etc.}$$

Thus in general  $E^n f(x) = f(x + nh)$  or  $E^n y_x = y_{x + nh}$ .

(b) **Averaging operator.** The averaging operator  $\mu$  is defined as

$$\mu f(x) = \frac{1}{2} \left[ f\left(x + \frac{1}{2} h\right) + f\left(x - \frac{1}{2} h\right) \right]$$

or

$$\mu y_x = \frac{1}{2} [y_{x + 1/2 h} + y_{x - 1/2 h}].$$

REMARK :

• The shift operator is also known as increment operator.

(vii) **Relations between the operators.** We shall have following identities :

(a)  $\Delta = E - 1$

(b)  $\nabla = 1 - E^{-1}$

(c)  $\delta = E^{1/2} - E^{-1/2}$

(d)  $\Delta = E\nabla = \nabla E = \delta E^{1/2}$

(e)  $E = e^{hD}$

(f)  $\mu = \frac{1}{2} (E^{1/2} + E^{-1/2})$ .

**Proof.** (a) Since

$$\Delta y_x = y_{x+h} - y_x$$

$$= E y_x - y_x \quad \text{for all } x$$

$$= (E - 1) y_x \quad \text{for all } x$$

$$\Delta = E - 1 \text{ or } E = 1 + \Delta.$$

(b) Since

$$\begin{aligned} \nabla y_x &= y_x - y_{x-h} \\ &= y_x - E^{-1} y_x \text{ for all } x \end{aligned}$$

$$\nabla y_x = (1 - E^{-1}) y_x \text{ for all } x$$

$\therefore$

$$\nabla = 1 - E^{-1}.$$

(c) Since

$$\begin{aligned} \delta y_x &= y_{x+h/2} - y_{x-1/2 h} \\ &= E^{1/2} y_x - E^{-1/2} y_x \text{ for all } x \\ &= (E^{1/2} - E^{-1/2}) y_x \text{ for all } x \end{aligned}$$

$\therefore$

$$\delta = E^{1/2} - E^{-1/2}.$$

(d)

$$\begin{aligned} E \nabla y_x &= E(y_x - y_{x-h}) \\ &= E y_x - E y_{x-h} \text{ for all } x \\ &= y_{x+h} - y_x \text{ for all } x \\ &= \Delta y_x \end{aligned}$$

$\therefore$

$$E \nabla = \Delta$$

and

$$\begin{aligned} \nabla E y_x &= \nabla y_{x+h} \text{ for all } x \\ &= y_{x+h} - y_x \text{ for all } x \\ &= \Delta y_x \end{aligned} \quad \dots(1)$$

$\therefore$

$$\nabla E = \Delta. \quad \dots(2)$$

From (1) and (2)

$$\Delta = E \nabla = \nabla E.$$

(e) Since

$$\begin{aligned} E f(x) &= f(x+h) \\ &= f(x) + h f'(x) + \frac{h^2}{2!} f''(x) + \dots \text{ [By Taylor's Theorem]} \\ &= f(x) + h D f(x) + \frac{h^2}{2!} D^2 f(x) + \dots \\ &= \left( 1 + hD + \frac{h^2}{2!} D^2 + \dots \right) f(x) \end{aligned}$$

$$E f(x) = e^{hD} f(x)$$

$\therefore$

$$E = e^{hD} \text{ for all } x.$$

(f) By the definition of averaging operator, we have

$$\begin{aligned} \mu y_x &= \frac{1}{2} [y_{x+1/2 h} + y_{x-1/2 h}] \\ &= \frac{1}{2} [(E^{1/2} + E^{-1/2}) y_x] \end{aligned}$$

[By the definition of shift operator]

$\therefore$

$$\mu y_x = \frac{1}{2} [E^{1/2} + E^{-1/2}] y_x.$$

This is true for all  $x$ , therefore

$$\mu = \frac{1}{2} (E^{1/2} + E^{-1/2}).$$

(viii) The difference scheme is constructed in the following table :

$x$	$y$	First Diff.	Second Diff.	Third Diff.	Fourth Diff.	Fifth Diff.
$x_0$	$y_0$	$\Delta y_0$				
$x_1$	$y_1$	$\Delta y_1$	$\Delta^2 y_0$			
$x_2$	$y_2$	$\Delta y_2$	$\Delta^2 y_1$	$\Delta^3 y_0$		
$x_3$	$y_3$	$\Delta y_3$	$\Delta^2 y_2$	$\Delta^3 y_1$	$\Delta^4 y_0$	
$x_4$	$y_4$	$\Delta y_4$	$\Delta^2 y_3$	$\Delta^3 y_2$	$\Delta^4 y_1$	$\Delta^5 y_0$
$x_5$	$y_5$					

In the above  $\Delta^k y_0$  lie on a straight line down to right. On the other hand, since  $\Delta = E\nabla$ , we have,  $\Delta y_4 = \nabla y_5$ ,  $\Delta^2 y_3 = \nabla^3 y_5$ ,  $\Delta^3 y_2 = \nabla^3 y_5$  and so on, further since  $\nabla^k y_n$  lie on a straight line sloping downward to the right. Similarly we also have  $\Delta = E^{1/2} \delta$  and hence, we have  $\Delta^2 y_1 = E\delta^2 y_1 = \delta^2 y_2$ ,  $\Delta^4 y_0 = \delta^2 y_2$  and so on. In this way, we can observe that  $\delta^{2k} y_k$  lie on a horizontal line.

(ix) **Effect of an error on a difference table.** Let  $y_0, y_1, y_2, \dots, y_n$  be the values of function at  $x = x_0, x_1, x_2 \dots x_n$  and  $\epsilon$  be an error in the value  $y_5$ . Then the value of  $y_0$  with error is  $y_5 + \epsilon$ .

The table will be as under.

$x$	$y$	$\Delta y$	$\Delta^2 y$	$\Delta^3 y$	$\Delta^4 y$
$x_0$	$y_0$				
$x_1$	$y_1$	$\Delta y_0$			
$x_2$	$y_2$	$\Delta y_1$	$\Delta^2 y_0$		
$x_3$	$y_3$	$\Delta y_2$	$\Delta^2 y_1$	$\Delta^3 y_0$	
$x_4$	$y_4$	$\Delta y_3$	$\Delta^2 y_2$	$\Delta^3 y_1$	$\Delta^4 y_0$
$x_5$	$y_5 + \epsilon$	$\Delta y_4 + \epsilon$	$\Delta^2 y_3 + \epsilon$	$\Delta^3 y_2 + \epsilon$	$\Delta^4 y_1 + \epsilon$
$x_6$	$y_6$	$\Delta y_5 - \epsilon$	$\Delta^2 y_4 - 2\epsilon$	$\Delta^3 y_3 - 3\epsilon$	$\Delta^4 y_2 - 4\epsilon$
$x_7$	$y_7$	$\Delta y_6$	$\Delta^2 y_5 + \epsilon$	$\Delta^3 y_4 + 3\epsilon$	$\Delta^4 y_3 + 6\epsilon$
$x_8$	$y_8$	$\Delta y_7$	$\Delta^2 y_6$	$\Delta^3 y_5 + \epsilon$	$\Delta^4 y_4 - 4\epsilon$
$x_9$	$y_9$	$\Delta y_8$	$\Delta^2 y_7$	$\Delta^3 y_6$	$\Delta^4 y_5 + \epsilon$
$x_{10}$	$y_{10}$	$\Delta y_9$	$\Delta^2 y_8$	$\Delta^3 y_7$	$\Delta^4 y_6$

It is clear from above table that :

- (i) The error propagates in a triangular pattern and grows rapidly.
- (ii) The error increases with the increasing the order of differences.
- (iii) The coefficients of  $\epsilon$ 's in any column are the binomial coefficient of  $(1 - \epsilon)^n$ .
- (iv) The algebraic sum of the errors in any difference column is zero.